Common Fixed Point for Compatible Mappings on a 2-Metric Space

K.P.R. Sastry¹, G.A. Naidu², K.K.M. Sharma³ and I. Laxmi Gayatri⁴

 ¹8-28-8/1, Tamil Street, Chinna Waltair, Visakhapatnam-530 017, India E-mail: kprsastry@hotmail.com
 ²Associate Professor Department of Mathematics, Andhra University, Visakhapatnam-530 003, India. E-mail: drgolivean@yahoo.com
 ³Associate Professor Department of Mathematics, Andhra University, Visakhapatnam-530 003, India. E-mail: sarmakmkandala@yahoo.in
 ⁴Assistant Professor Department of Engg. Mathematics, GIT, GITAM University, Visakhapatnam-530 045, India. E-mail: ilg.gitam@gmail.com

Abstract

The aim of the present paper is to obtain i) a common fixed point theorem for compatible mappings by using the concept of asymptotic regularity and ii) a common fixed point theorem using the concept of joint reciprocal continuity in 2- metric spaces. A supporting example is also given.

Keywords: common fixed point, Compatible mappings and asymptotic regularity.

Mathematical subject Classification : 47 H 10,54H25

Introduction

 $G^{\bar{\alpha}}$ hler[2] introduced the concept of 2-metric space as a natural generalization of a metric space. Some fixed point theorems in 2-metric spaces are obtained in Iseki[3],Rhoades[5] and Jungck[4]. $G^{\bar{\alpha}}$ hler[2] introduced the notions of reciprocal continuity and asymptotic regularity for a pair of self maps on a 2-metric space. Using the above concepts Badshah and Gopal Meena[1] proved a fixed point theorem for a pair of self-maps on a 2-metric space using asymptotic regularity.

The present paper is a generalization of a result of Badshah and Gopal

Meena([1], Theorem 2).

In this paper, we obtain i) a common fixed point theorem (Th. (2.1)) for compatible mappings by using the concept of asymptotic regularity and ii) a common fixed point theorem (Th. (2.6)) using the concept of joint reciprocal continuity. We start with some definitions.

Definition 1.1 (G \bar{a} **hler[2]):** Let X be a non-empty set with real valued function $d: X^{\mathbb{S}} \to R$ satisfying :

For two distinct points x, y in X, there exists z in X such that $d(x, y, z) \neq 0$ d(x, y, z) = 0 only if at least two of x, y and z are equal d(x, y, z) = d(x, z, y) = d(y, z, x) and $d(x, y, z) \leq d(x, y, u) + d(x, u, z) + d(u, y, z)$ for all x, y, z, u in X.

The function d is called a 2-metric on X and the pair (X, d) is called a 2-metric space.

Definition 1.2 (G^{$\bar{\alpha}$}**hler[2]) :** Let (X, d) be a 2-metric space . A sequence $\{x_n\}$ is said to be convergent to a point $x \ln X \text{ tf } \lim_{n \to \infty} d(x_n, x, a) = 0, \forall a \in X.$

A sequence $\{x_n\}$ is said to be a Cauchy sequence in X $\lim_{n \to \infty} d(x_m, x_n, a) = 0, \forall a \in X$.

A 2-metric space (X, d) is said to be complete if every Cauchy sequence in X converges to a point in X.

Note: i) In a 2-metric space $(X, d), d: X^8 \to R$ is continuous if $x_n \to x$, $y_n \to y$ implies $d(x_n, y_n, a) \to d(x, y, a), \forall a \in X$ for $n \to \infty$.

ii) If $x_n \rightarrow x$ and $x_n \rightarrow y$ as $n \rightarrow \infty$ then x = y.

Definition 1.3 (G^{\bar{a}}**hler[2]):** For self-mappings, S and T of a 2-metric space (X, d), the pair (S, T) is called reciprocally continuous if $\lim_{n \to \infty} d(STx_n, Sx, a) = 0 = d(TSx_n, Tx, a) \forall a \in X$, whenever $\{x_n\}$ is a sequence in X such that $\lim_{n \to \infty} Sx_n = \lim_{n \to \infty} Tx_n = x$, for some $x \in X$.

Definition 1.4 (G^{\bar{a}}**hler[2]):** For self-mappings, S and T of a 2-metric space (X, d)A sequence $\{x_n\}$ in X is called asymptotically regular with respect to the pair (S,T) if $\lim_{n \to \infty} d(Sx_n, Tx_n, a) = 0$ va $\in X$.

The pair (S,T) is called compatible if $\lim_{n \to \infty} d(STx_n, TSx_n, a) = 0 \forall a \in X$, whenever $\{x_n\}$ is a sequence in

156

Common Fixed Point for Compatible Mappings

X such that $\lim_{n \to \infty} Sx_n = \lim_{n \to \infty} Tx_n = x$, for some $x \in X$.

Definition 1.5: Suppose *P*, *S* and *T* are self maps on a 2-metric space (*X*, *d*). The pair (*S*, *T*) is said to be joint reciprocal continuous with respect to *P* if there exists a sequence $\{x_n\}$ in *X* such that $\lim_{n \to \infty} Sx_n = \lim_{n \to \infty} Tx_n$ and $\lim_{n \to \infty} d(PSx_n, SPx_n, a) = 0$ and $\lim_{n \to \infty} d(PTx_n, TPx_n, a) = 0$ $\forall a \in X$

Note : If $\{x_n\}$ is a sequence in X such that $\lim_{n \to \infty} Sx_n = \lim_{n \to \infty} Tx_n$ and (P, S) and (P, T) are compatible then (S, T) is jointly reciprocally continuous with respect to P.

Notation: $\Phi = \{\varphi | \varphi : [0, \infty) \rightarrow [0, \infty), \varphi \text{ is continous and } \varphi \{t\} < t \forall t > 0 \}$

Main Results

We begin with our first main result, from this we obtain corollaries of the main result and finally show that the result of Badshah and Gopal Meena[1] follows as a corollary.

Theorem 2.1: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying:

 $\begin{array}{ll} l) d(Px, Py, a) \leq & \varphi \left(\max \left[\left\{ d(Py, Ty, a) (1 + d(Px, Sx, a)), d(Px, Sx, a) (1 + & d(Py, Ty, a), d(Px, Sx, a), d(Py, Sy, a) \right\} \right] \right) \\ \forall x, y, a \in X \ and \ for \ some \ \varphi \in \Phi, \\ il) \ the \ pair \ (P, S) \ and \ (P, T) \ are \ compatible \\ \end{array}$

(11) there exists a sequence $\{x_n\}$ which is asymptotically regular with respect (P, S) and (P, T)

iv) S and T are continous v) d is continous.

Then *P*, *S* and *T* have a unique common fixed point in X.

Proof: Let $\{x_n\}$ be a sequence in X satisfying condition ((11)). By taking $x = x_n$ and $y = x_m$ in (1), we obtain

$$\left[d(Px_{n},Px_{m}a) \leq \varphi \left[(\max] \left\{ d(Px_{m},Tx_{m},a) \left(1 + d(Px_{n},Sx_{n},a)\right), \quad d(Px_{n},Sx_{n},a) \left(1 + (Px_{m},Tx_{m},a)\right), d(Px_{n},Sx_{n},a), d(Px_{m},Sx_{m},a) \right\} \right)$$

$$(2.1.1)$$

On letting $n \to \infty$ and using condition (*ttt*), we get $\lim_{n \to \infty} d(Px_n, Px_m, a) = 0 \forall a \in X$

This implies that the sequence $[Px_n]$ is a Cauchy sequence in X, since X is complete with respect to 2-metric d.

This implies

11

 $Px_n \rightarrow z$, for some zeX (2.1.2)Now $d(Sx_n, z, a) \leq d(Sx_n, z, Px_n) + d(Sx_n, Px_n, a) + d(Px_n, z, a)$ On letting $n \rightarrow \infty$, using condition (11) and equation (2.1.2), we get $\lim_{n \to \infty} d(Sx_n, z, a) = 0 \quad \forall a \in X.$ This implies $Sx_n \rightarrow z \ln X$. (2.1.3)Similarly we can obtain $Tx_n \rightarrow z \ tn \ X.$ (2.1.4)Since we can write $d(PSx_n, Sz, a) \leq d(PSx_n, Sz, SPx_n) + d(PSx_n, SPx_n, a) + d(SPx_n, Sz, a)$ On letting $n \to \infty$, using the conditions (11), (1v) and (v), we get $\lim_{n \to \infty} d(PSx_n, Sz, a) = 0 \ \forall a \in X,$ (• $Px_n \rightarrow z$ and S is continuous implies $SPx_n \rightarrow Sz$) This implies $PSx_n \rightarrow Sz$. (2.1.5)Similarly we can prove $PTx_n \rightarrow Tz$. (2.1.6)By taking $x = Sx_n$ and $y = Tx_n$ in (1), we obtain $d(PSx) \downarrow n, PTx_1n, a) \leq \varphi(max\{ Ld(PTx) \downarrow n, TTx_1n, a)(1 + Ld(PSx) \downarrow n, SSx_1n, a)),$ $\llbracket d(PSx \rrbracket_n, SSx_n, a)(1 + \llbracket d(PTx \rrbracket_n, TTx_n, a)),$ $d(PSx \mid n, SSx_n, a), d(PTx \mid n, STx_n, a))$ (2.1.7)From condition (iv) we have S and T are continuous, applying continuity of **S** and **T** in (2.1.3) and (2.1.4), we get $SSx_n \rightarrow Sz_iTTx_n \rightarrow Tz$ and $STx_n \rightarrow Sz$ (2.1.8)On letting $n \rightarrow \infty$ in (2.1.7), using (2.1.5),(2.1.6),(2.1.8) and condition (v), we get $d(Tz, Sz, a) = 0, \forall a \in X$. This implies Tz = Sz.(2.1.9)Similarly by taking $x = Tx_n$ and $y = z \ln(t)$, we get $d(PTx_1n, Pz, a) \leq \varphi(\max\{d(Pz, Tz, a)(1 + d(PTx_1n, STx_1n, a), d(PTx_1n, STx_1n, a)(1 + d(Pz, Tz, a)), d(PTx_1n, STx_1n, a), d(Pz, Sz, a)\})$ On letting $n \rightarrow \infty$, using ((2.1.7),(2.1.8),(2.1.9) and condition(v), we get $d(Tz, Pz, a) = 0, \forall a \in X$. This implies Tz = Pz.(2.1.10)Therefore Sz = Tz = Pz. (2.1.11)By taking $x = x_n$ and y = z in (i), we get $d(Px_1n, Pz, a) \leq \|\varphi(\max)\|\{d(Pz, Tz, a)(1 + d(Px_1n, Sx_1n, a), d(Px_1n, Sx_1n, a)(1 + d(Pz, Tz, a), d(Px_1n, Sx_1n, a), d(Pz, Tz, a)\}\}$ On letting $n \rightarrow \infty$ and using (2.1.2),(2.1.3),(2.1.11) and condition(iv), we get $d(z, Pz, a) = 0, \forall a \in X$ This implies Pz = z. z is a fixed point of P. Hence z is a common fixed point of Therefore S, T and P in X.

Suppose if x is common fixed point of S,T and P in X. Then it can be easily proved that x = z. Hence z is a unique common fixed point of S,T and P in X. Now we have the following corollaries of theorem 2.1.

158

Corollary 2.2 : Let P, S and T be self-mappings of a complete 2-metric space (X, d)satisfying:

i) $d(Px, Py, a) \leq \lambda \max \{ \{ d(Py, Ty, a)(1 + d(Px, Sx, a)), d(Px, Sx, a)(1 + d(Py, Ty, a), d(Px, Sx, a), d(Py, Sy, a) \} \}$ $\forall x, y, a \in X, 0 < \lambda < 1$ and also satisfying condition ((1), ((11), (11)) and (v) of theorem 2.1.

Then *P*, *S* and *T* have a unique common fixed point in X.

Corollary 2.3: Let P, S and T be self-mappings of a complete 2-metric space (X, d)satisfying:

t) $d(Px, Py, a) \leq \alpha \max \{ d(Py, Ty, a)(1 + d(Px, Sx, a)), d(Px, Sx, a)(1 + d(Py, Ty, a)) \} + \beta \max\{ d(Px, Sx, a), d(Py, Sy, a) \} \}$ $\forall x, y, a \in X$, a and β are non – negative numbers such that $a + \beta < 1$ and also satisfying condition (11), (111), (112) and (12) of theorem 2.1.

Then **P**, **S** and **T** have a unique common fixed point in X.

Corollary 2.4: Let P, S and T be self-mappings of a complete 2-metric space (X, d)satisfying:

i) $d(Px, Py, a) \leq \alpha \left[d(Py, Ty, a)(1 + d(Px, Sx, a)) + \right] \beta \left\{ d(Px, Sx, a) + d(Py, Sy, a) \right\}$ $\forall x, y, a \in X$, α and β are non - negative numbers such that $\alpha + \beta < 1$ and also satisfying condition (11), (111), (112) and (12) of theorem 2.1.

Then *P*, *S* and *T* have a unique common fixed point in X.

The following result due to Badshah and Gopal Meena[1] is a corollary of the above result.

Corollary 2.5 (Badshah and Gopal Meena[1], Theorem 2): Let \mathbb{P} , S and T be self-mappings of a complete 2-metric space (X, d) satisfying:

```
() d(Px, Pv, a) \leq \alpha d(Pv, Tv, a)(1 + d(Px, Sx, a))/(1 + d(Sx, Tv, a))
+\beta\{d(Px, Sx, a) + d(Py, Sy, a\}
```

 $\forall x, y, a \in X$, α and β are non – negative numbers such that $\alpha + \beta < 1$. and also satisfying condition (11), (111), (112) and (12) of theorem 2.1.

Then P, S and T have a unique common fixed point in X.

Now we state our second main result which uses the concept of joint reciprocal continuity.

Theorem 2.6: Let P, S and T be self-mappings of a complete 2-metric space (X, d)satisfying: $\max[\{d(Py,Ty,a)\{1+d(Px,Sx,a)\},$ d(Px, Sx, a)(1 + d(Py, Ty, a), d(Px, Sx, a), d(Py, Sy, a)))) $\forall x, y, a \in X and 0 < \lambda < 1$ ii) S and T are continous iii) d is continous. iv) (S,T) is joint reciprocal continous w.r.t. P in X Then *P*, *S* and *T* have a unique common fixed point in X.

```
160
```

```
Proof: From condition(lv) there exists a sequence \{x_n\} in X such that
```

 $\lim_{n \to \infty} Sx_n = \lim_{n \to \infty} Px_n = \lim_{n \to \infty} Tx_n = z \text{ for some } z \in X$ (2.5.1) and

$$\lim_{n \to \infty} d(PSx_n, SPx_n, a) = 0 = \lim_{n \to \infty} d(PTx_n, TPx_n, a) \forall a \in X$$
(2.5.2)

Applying *condition (11)* in equation (2.5.1) and using this in the equation (2.5.2), we get

$$PSx_n \rightarrow Sz \text{ and } PTx_n \rightarrow Tz$$
 (2.5.3)

By taking $x = Sx_{n_x}y = Tx_n$ in (1) and letting $n \to \infty$, using conditions (ii), (iii) and (2.5.2) and (2.5.3), we get Sz = Tz. (as derived in theorem 2.1)

Similarly taking $x = Tx_n$ and y = z in (1) and letting $n \to \infty$, we get

Pz = Tz (as derived in theorem 2.1). Therefore Sz = Pz = Tz.

Taking $x = x_n$ and $y = z \ln (t)$ and letting $n \to \infty$, we get z = Pz.

This is z is a fixed point of P. Hence z is a common fixed point of S. T and P in X. Suppose if x is common fixed point of S. T and P in X. Then it can be easily proved that x = z. Hence z is a unique common fixed point of S. T and P in X.

Now we have the following corollaries of theorem 2.6.

Corollary 2.7: Let *P*.*S* and *T* be self-mappings of a complete 2-metric space (X, d) satisfying: condition (i) of corollary (2.2) and conditions (U), (U) and (U) of theorem (2.6).

Then P, S and T have a unique common fixed point in X.

Corollary 2.8: Let *P*.*S* and *T* be self-mappings of a complete 2-metric space (X, d) satisfying: conditions (i) of corollary(2.3) and also conditions (*tt*). (*ttt*) and (*tv*) of theorem (2.6).

Then P, S and T have a unique common fixed point in X.

Corollary 2.9: Let *P*.*S* and *T* be self-mappings of a complete 2-metric space (X, d) satisfying: conditions (i) of corollary (2.4) and also conditions (ii) (iii) and (iv) of theorem (2.6).

Then P, S and T have a unique common fixed point in X.

Corollary 2.10: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying:

conditions (i) of corollary 2.5 and also the conditions (ii) (iii) and (iv) of theorem (2.6).

Then P, S and T have a unique common fixed point in X.

Example 2.11:

Let $X = R \times R$ for $A, B \in X$, denote the Euclidean distance A and B by |A - B|.

Define $d: X^{\circ} \to R$ by $d(A, B, C) = \min\{A - B\}, |B - C|, |C - A|\}$. Then (X, d) is a complete 2-metric space. Let $A_{\circ} \in X$. Define the mappings

 $P, S and T on X as P(A) = A_0 \forall A \in X and S = T = I.$

Define $\varphi(t) = \eta t, 0 < \eta < 1$ then $\varphi \in \Phi$. Then *P*, *S* and *T* satisfy all the properties of Theorem 2.1 and Theorem 2.6 and A_0 is the unique common fixed point of *P*, *S* and *T* in *X*.

Acknowledgment

The fourth author is grateful to GITAM University Authorities, GITAM University, Vishakhapatnam for support of this work.

References

- [1] Badshah,V.H. and Gopal Meena: Common fixed point for compatible mappings on 2-metric space, Journal of Indian Acad. Math.Vol 31, No.1 (2009), 23-30.
- [2] G^āhler,S.: 2-metrische R^āume und ihre toplogische structure, Math.Nachr.26(1963-64),115-148.
- [3] Iseki,K: Fixed point theorem in 2-metric spaces . Math. Sem. Notes 3(1975),133-136.
- [4] Jungck,G.: Compatible mappings and common fixed points, Internat. J.Math. and Math.Sci. 9(1986), 771-779.
- [5] Rhoades, B.: Contraction type mappings on a 2-mertic space, Math.Nach, 91(1979), 151-155.