

## A Common Fixed Point Theorem in Cone Metric Spaces under S-Type Control Function

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### Abstract

In this paper we prove the existence of coincidence points and common fixed points for large class of a almost contractions in cone metric spaces and obtain results of Berinde as a corollary in S -cone metric spaces.

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### Introduction

In this section, we introduce the familiar notions of cone metric spaces, and state the results of Berinde, which we need in the next section.

**Definition 1.1 (S. Rezapour [7]):** Let  $E$  be a real Banach space and  $P$  a subset of  $E$ .  $P$  is called a cone if

- (i)  $P$  is closed, non empty and  $P \neq \{0\}$ ;
- (ii)  $ax + by \in P \forall x, y \in P$  and non negative real numbers  $a, b$ ;

$$(iii) \quad P \cap (-P) = \{0\}.$$

Note also that the relations  $int P + int P \subseteq int P$  and  $\lambda int P \subseteq int P$  ( $\lambda > 0$ ) hold. For a given cone  $P \subseteq E$ , we can define on  $E$  a partial ordering  $\leq$  with respect to  $P$  by putting  $x \leq y$  if and only if  $y - x \in P$ . Further,  $x < y$  stands for  $x \leq y$  and  $x \neq y$ , while  $x \ll y$  stands for  $y - x \in int P$ , where  $int P$  denotes the interior of  $P$ .

**Definition 1.2 (L.G. Huang [5]):** Let  $X$  be a nonempty set. A mapping  $d: X \times X \rightarrow E$  satisfying

- (i)  $0 \leq d(x, y) \forall x, y \in X$  and  $d(x, y) = 0$  if and only if  $x = y$ ;
- (ii)  $d(x, y) = d(y, x) \forall x, y \in X$ ;
- (iii)  $d(x, y) \leq d(x, z) + d(z, y) \forall x, y, z \in X$ ,

is called a cone metric on  $X$ , while  $(X, d)$  is called a cone metric space.

**Example 1.3:** Let  $(X, d_1), (X, d_2)$  be two metric spaces (that is,  $d_1, d_2$  are two metrics on the same underlying space  $X$ ). Let  $E = R^2$  be the Euclidean plane and

$P = \{(x, y) \in R^2 : x, y \geq 0\}$ . Then  $P$  is a cone in  $E$ . Define  $d: X \times X \rightarrow P$  by

$$d(x, y) = (d_1(x, y), d_2(x, y)) \forall x, y \in X; \text{ Then } (X, d) \text{ is a cone metric space.}$$

**Note:** If  $\alpha, \beta > 0$  and if we define  $d(x, y) = (\alpha d_1(x, y), \beta d_2(x, y)) \forall x, y \in X$ , then  $d$  is also cone metric on  $X$ .

**Definition 1.4 (L.G. Huang [5]):** Let  $(X, d)$  be a cone metric space,  $x \in X$  and  $\{x_n\}_{n \geq 1}$  a sequence in  $X$ . Then

- (i)  $\{x_n\}_{n \geq 1}$  converges to  $x$  whenever for every  $\varepsilon \in E$  with  $0 \ll \varepsilon$ , there is a natural number  $N$  such that  $d((x_n, x)) \ll \varepsilon$  for all  $n \geq N$ . We denote this by  $\lim_{n \rightarrow \infty} x_n = x$  or  $x_n \rightarrow x$ , as in the usual case.
- (ii)  $\{x_n\}_{n \geq 1}$  is a Cauchy sequence whenever for every  $\varepsilon \in E$  with  $0 \ll \varepsilon$  there is a natural number  $N$  such that  $d(x_{n+p}, x_n) \ll \varepsilon$  for all  $n \geq N$  and all  $p$ ;
- (iii)  $(X, d)$  is a complete cone metric space if every Cauchy sequence is convergent.

**Definition 1.5 (M. Abbas [1]):** Let  $S$  and  $T$  be self maps of a nonempty set  $X$ . If there exists  $x \in X$  such that  $Sx = Tx$  then  $x$  is called a coincidence point of  $S$  and  $T$ , while  $y = Sx = Tx$  is called a point of coincidence of  $S$  and  $T$ .

If  $Sx = Tx = x$ , then  $x$  is a common fixed point of  $S$  and  $T$ .

**Definition 1.6 (G. Jungck [6]):** Let  $S$  and  $T$  be self maps of a nonempty set  $X$ . The pair  $(S, T)$  of mappings is said to be weakly compatible if they commute at their coincidence points.

The next proposition (M. Abbas and G. Jungck [1], Proposition 1.4) will be needed in our main result.

**Proposition 1.7:** Let  $S$  and  $T$  be weakly compatible self maps of a nonempty set  $X$ .

If  $S$  and  $T$  have a unique point of coincidence  $y = Sx = Tx$ , then  $y$  is the unique common fixed point of  $S$  and  $T$ .

Berinde [3] proved the following theorem for an almost contractive self map on a complete metric space

**Theorem 1.8 (V. Berinde [4], Theorem 1):** Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow X$  an almost contraction, that is a mapping for which there exist a constant  $\delta \in (0,1)$  and some  $L \geq 0$  such that

$$d(Tx, Ty) \leq \delta \cdot d(x, y) + Ld(y, Tx), \text{ for all } x, y \in X \dots \quad (1.8.1)$$

Then

1.  $F(T) = \{x \in X : Tx = x\} \neq \emptyset$  ;
2. For any  $x_0 \in X$ , the Picard iteration  $\{x_n\}_{n=0}^\infty$  given by  $x_{n+1} = Tx_n$  converges to some  $x^* \in F(T)$ ;
3. The following estimate holds  $d(x_{n+i-1}, x^*) \leq \frac{\delta^i}{1-\delta} d(x_n, x_{n-1})$  ,  $n = 0, 1, 2, \dots, i = 1, 2, \dots$

This theorem concludes that  $T$  has a fixed point. However, the fixed point need not be unique in view of the following example.

**Example 1.9:** Define  $T: \{0,1\} \rightarrow \{0,1\}$  by  $T(x) = \begin{cases} 0 & \text{if } x = 0 \\ 1 & \text{if } x = 1 \end{cases}$

Then  $T$  satisfies (1.8.1) and  $T$  has two fixed points.

Berinde [4] extended this result as a coincidence theorem to two self maps on a cone metric space  $(X, d)$  as follows

**Theorem 1.10 (V. Berinde [4], Theorem 2):** Let  $(X, d)$  be a cone metric space and let  $T, S : X \rightarrow X$  be two mappings for which there exist a constant  $\delta \in (0, 1)$  and some  $L \geq 0$  such that

$$d(Tx, Ty) \leq \delta d(Sx, Sy) + Ld(Sy, Tx), \text{ for all } x, y \in X \quad (1.10.1)$$

If the range of  $S$  contains the range of  $T$  and  $S(X)$  is a complete subspace of  $X$ , then  $T$  and  $S$  have a coincidence point in  $X$ . Moreover, for any  $x_0 \in X$ , the iteration  $\{Sx_n\}$  defined by  $Sx_{n+1} = Tx_n$  converges to some coincidence point  $x^*$  of  $T$  and  $S$ .

The coincidence point obtained from theorem (1.10) need not be unique in view of example (1.9) (by taking  $S = T$ ).

In order to obtain a common fixed point theorem from the above coincidence point theorem Berinde [4] imposed an additional contractive condition which makes the coincidence point unique and hence becomes a common fixed point.

**Theorem 1.11 (V. Berinde [4], Theorem 3):** Let  $(X, d)$  be a cone metric space and let  $T, S : X \rightarrow X$  be two mappings satisfying (1.10.1) for which there exist a constant

$\theta \in (0, 1)$  and some  $L_1 \geq 0$  such that

$$d(Tx, Ty) \leq \theta d(Sx, Sy) + L_1 d(Sx, Tx), \text{ for all } x, y \in X, \quad (1.11.1)$$

If the range of  $S$  contains the range of  $T$  and  $S(X)$  is a complete subspace of  $X$ , then  $T$  and  $S$  have a unique coincidence point in  $X$ . Moreover, if  $T$  and  $S$  are weakly compatible, then  $T$  and  $S$  have a unique common fixed point in  $X$ . In both cases, for any  $x_0 \in X$ , the iteration  $\{Sx_n\}$  defined by  $Sx_{n+1} = Tx_n$  converges to the unique common fixed point (coincidence point)  $x^*$  of  $S$  and  $T$ .

Babu et.al [3] unified (1.10.1) and (1.11.1) in the metric space context for a single map and obtained the following theorem.

**Theorem 1.12 (G. V. R. Babu [2], Theorem 2.3):** Let  $(X, d)$  be a complete metric space and let  $T : X \rightarrow X$  be a map satisfying the condition

$$d(Tx, Ty) \leq \delta d(x, y) + L \min\{d(x, Tx), d(y, Ty), d(x, Ty), d(y, Tx)\}$$

Then  $T$  has a unique common fixed point.

In the cone metric space context of the above theorem, Berinde [4] has proved the following Theorem 1.13.

**Theorem 1.13 (V. Berinde [4], Theorem 4):** Let  $(X, d)$  be a cone metric space and let  $T, S : X \rightarrow X$  be two mappings for which there exist a constant  $\delta \in (0, 1)$  and some  $L \geq 0$  such that

$$d(Tx, Ty) \leq \delta d(Sx, Sy) + L \min\{d(Sx, Tx), d(Sy, Ty), d(Sx, Ty), d(Sy, Tx)\} \quad (1.13.1)$$

for all  $x, y \in X$ . If the range of  $S$  contains the range of  $T$  and  $S(X)$  is a complete subspace of  $X$ , then  $T$  and  $S$  have a unique coincidence point in  $X$ . Moreover, if  $T$  and  $S$  are weakly compatible, then  $T$  and  $S$  have a unique common fixed point in  $X$ . In both cases, for any  $x_0 \in X$ , the iteration  $\{Sx_n\}$  defined by  $Sx_{n+1} = Tx_n$  converges to the unique common fixed point (coincidence point)  $x^*$  of  $S$  and  $T$ .

**Note:** In Theorem 1.13 the right hand side of the equation (1.13.1) may not be meaningful, since  $\min\{d(Sx, Tx), d(Sy, Ty), d(Sx, Ty), d(Sy, Tx)\}$  may not exist in  $P$  (cone of  $E$ ).

In order to overcome this difficulty, in the next section we introduce the concept of S-type control function, and obtain a satisfactory account of the above theorem.

## Main results

In this section we introduce the concept of S-type control function and obtain a satisfactory account of theorem (1.13)

**Definition 2.1:** Let  $E$  be a real Banach space and  $P$  a cone in  $E$ . Suppose  $\varphi : P^4 \rightarrow P$  is a continuous function which satisfies the condition.

(S) :  $\varphi(t_1, t_2, t_3, t_4) = 0$  if any one of  $t_1, t_2, t_3, t_4$  is zero.

Then  $\varphi$  is called a S– type control function.

**Example 2.2:** Let  $E$  be a Banach space,  $P$  be a cone in  $E$ . Let  $t_1, t_2, t_3, t_4$  be bounded linear functionals on  $E$ . Define  $\varphi: P^4 \rightarrow P$  by

$$\varphi(t_1, t_2, t_3, t_4) = |f_1(t_1) \cdot f_2(t_2) \cdot f_3(t_3) \cdot f_4(t_4)| (t_1 + t_2 + t_3 + t_4)$$

Then  $\varphi$  is continuous and satisfies  $\varphi(t_1, t_2, t_3, t_4) = 0$  if any one of  $t_1, t_2, t_3, t_4$  is zero. Thus  $\varphi$  is a S - type control function.

**Definition 2.3:** Let  $(X, d)$  be a cone metric space with normal cone  $P$  and normal constant  $K$ . Suppose  $S = \{d(x, y): x, y \in X\}$  is a totally ordered subset of  $P$ . Then  $(X, d)$  is called a S –cone metric space.

**Example 2.4:** Let  $E = R^2$ ,  $P = \{(x, y) \in E: x \geq 0, y \geq 0\}$  and  $X = [0,1]$ .

Define  $d: X \times X \rightarrow P$  by  $d(x, y) = (|x - y|, \frac{1}{2}|x - y|)$ .

Then  $(X, d)$  is a S –cone metric space.

We observe that every metric space is a S - cone metric space.

**Example 2.5:** Let  $(X, d_1)$  be a metric space and  $\alpha > 0$ . Let  $E$  and  $P$  be as in Example 2.4. Define  $d: X \times X \rightarrow P$  by  $d(x, y) = (d_1(x, y), \alpha d_1(x, y)) \forall x, y \in X$ .

Then  $(X, d)$  is a S –cone metric space.

**Example 2.6:** Let  $(X, d)$  be a S – cone metric space and let  $S, T$  be self maps on  $X$ . Define  $\varphi(x, y) = \min\{d(Sx, Tx), d(Sy, Ty), d(Sx, Ty), d(Sy, Tx)\} \forall x, y \in X$ , then  $\varphi$  is a S - type control function.

**Theorem 2.7:** Let  $(X, d)$  be a cone metric space and let  $T, S: X \rightarrow X$  be two mappings for which there exist a constant  $\delta \in (0, 1)$  and a S – type control function  $\varphi$  such that

$$d(Tx, Ty) \leq \delta d(Sx, Sy) + \varphi\{d(Sx, Tx), d(Sy, Ty), d(Sx, Ty), d(Sy, Tx)\} \quad (2.7.1)$$

$\forall x, y \in X$ . If the range of  $S$  contains the range of  $T$  and  $S(X)$  is a complete subspace of  $X$ , then  $T$  and  $S$  have a unique coincidence point in  $X$ . Moreover, if  $T$  and  $S$  are weakly compatible, then  $T$  and  $S$  have a unique common fixed point in  $X$ . In both cases, for any  $x_0 \in X$ , the iteration  $\{Sx_n\}$  defined by  $Sx_{n+1} = Tx_n$  converges to the unique common fixed point (coincidence point)  $x^*$  of  $S$  and  $T$ .

**Proof:** Let  $x_0$  be an arbitrary point in  $X$ . Since  $T(X) \subset S(X)$ , we can choose a point  $x_1$  in  $X$  such that  $Tx_0 = Sx_1$ . Continuing in this way, for a  $x_n$  in  $X$ , we can find

$$x_{n+1} \in X \text{ such that } Sx_{n+1} = Tx_n, n = 0,1,2 \quad (2.7.2)$$

If  $x = x_{n-1}, y = x_n$  are two successive terms of the sequence defined by (2.7.2), then by ( 2.7.1) we have

$$\begin{aligned}
& d(Tx_{n-1}, Tx_n) \leq \delta d(Sx_{n-1}, Sx_n) \\
& + \varphi\{d(Sx_{n-1}, Tx_{n-1}), d(Sx_n, Tx_n), d(Sx_{n-1}, Tx_n), d(Sx_n, Tx_{n-1})\} \\
& \Rightarrow d(Tx_{n-1}, Tx_n) \leq \delta d(Tx_{n-2}, Tx_{n-1}) \\
& + \varphi\{d(Tx_{n-2}, Tx_{n-1}), d(Tx_{n-1}, Tx_n), d(Tx_{n-2}, Tx_n), d(Tx_{n-1}, Tx_{n-1})\}
\end{aligned}$$

In view of (2.7.2). since  $d(Tx_{n-1}, Tx_{n-1}) = 0$ , the above equation reduces to

$$\begin{aligned}
& d(Tx_{n-1}, Tx_n) \leq \delta d(Tx_{n-2}, Tx_{n-1}) \\
& d(Tx_{n-1}, Tx_n) \leq \delta^2 d(Tx_{n-3}, Tx_{n-2})
\end{aligned}$$

Hence, in general, we have

$$d(Tx_{n-1}, Tx_n) \leq \delta^{n-1} d(Tx_0, Tx_1) \quad (2.7.3)$$

Now for  $p \geq 1$ , we get

$$\begin{aligned}
& d(Tx_{n+p}, Tx_n) \leq d(Tx_{n+p}, Tx_{n+p-1}) + d(Tx_{n+p-1}, Tx_{n+p-2}) + \dots \\
& + d(Tx_{n+1}, Tx_n). \\
& \leq \delta^{n+p-1} d(Tx_0, Tx_1) + \delta^{n+p-2} d(Tx_0, Tx_1) + \dots + \delta^n d(Tx_0, Tx_1). \\
& = \delta^n (\delta^{p-1} + \delta^{p-2} + \dots + 1) d(Tx_0, Tx_1) \\
& = \frac{\delta^n (1 - \delta^p)}{1 - \delta} d(Tx_0, Tx_1) \\
& \leq \frac{\delta^n}{1 - \delta} d(Tx_0, Tx_1)
\end{aligned}$$

Let now  $0 \ll \varepsilon$  be given. Choose  $\lambda > 0$  such that  $\varepsilon + N_\lambda(0) \subset \text{int } P$ , where  $N_\lambda(0) = \{y \in E: \|y\| < \lambda\}$ . Also choose a natural number  $N_1$  such that

$$\frac{\delta^n}{1 - \delta} d(Tx_0, Tx_1) \in N_\lambda(0) \quad \forall n \geq N_1$$

$$\text{Then } \frac{\delta^n}{1 - \delta} d(Tx_0, Tx_1) \ll \varepsilon \quad \forall n \geq N_1$$

$$\text{And hence } d(Tx_{n+p}, Tx_n) \leq \frac{\delta^n}{1 - \delta} d(Tx_0, Tx_1) \ll \varepsilon, \quad \forall n \geq N_1$$

which shows that  $\{Tx_n\}$  is a Cauchy sequence and hence  $\{Sx_n\}$  is also Cauchy.

Since  $S(X)$  is complete, there exists a  $x^*$  in  $S(X)$  such that

$$\lim_{n \rightarrow \infty} Tx_n = \lim_{n \rightarrow \infty} Sx_n = x^* \dots \quad (2.7.4)$$

We can find  $p \in X$  such that  $Sp = x^*$  (since  $x^* \in S(X)$ )

Now we show that  $\{Tx_n\} \rightarrow Tp$

We have, by (2.7.1)

$$d(Tx_n, Tp) \leq \delta d(Sx_n, Sp) + \varphi\{d(Sx_n, Tx_n), d(Sp, Tp), d(Sx_n, Tp), d(Sp, Tx_n)\}$$

Letting  $n \rightarrow \infty$ , we get that

$$\begin{aligned}
 \lim_{n \rightarrow \infty} d(Tx_n, Tp) &\leq \lim_{n \rightarrow \infty} (\delta d(Sx_n, Sp) \\
 &\quad + \varphi\{d(Sx_n, Tx_n), d(Sp, Tp), d(Sx_n, Tp), d(Sp, Tx_n)\}) \\
 &= \lim_{n \rightarrow \infty} \delta d(Sx_n, Sp) \\
 &\quad + \varphi\{\lim_{n \rightarrow \infty} d(Sx_n, Tx_n), d(Sp, Tp), \lim_{n \rightarrow \infty} d(Sx_n, Tp), \lim_{n \rightarrow \infty} d(Sp, Tx_n)\} \\
 &= \delta d(x^*, x^*) + \varphi\{d(x^*, x^*), d(x^*, Tp), d(x^*, Tp), d(x^*, x^*)\} \\
 &= 0.
 \end{aligned}$$

So that  $\lim_{n \rightarrow \infty} d(Tx_n, Tp) \leq 0$

Hence  $\lim_{n \rightarrow \infty} d(Tx_n, Tp) = 0$

Thus  $Tx_n \rightarrow Tp \dots$  (2.7.5)

By (2.7.4) and (2.7.5) follows that  $Tp = Sp = x^*$

i.e.  $p$  is a coincidence point of  $T$  and  $S$ . ( or  $x^*$  is a point of coincidence of  $T$  and  $S$ ).

Now we prove that  $x^*$  (point of coincidence of  $T$  and  $S$ ) is unique.

Let  $Tx = Sx = y^*$  and  $Sp = Tp = x^*$  be two points of coincidence of  $T$  and  $S$ .

Then, we show that  $x^* = y^*$

We have, from

$$\begin{aligned}
 d(Tx, Tp) &\leq \delta d(Sx, Sp) + \varphi\{d(Sx, Tx), d(Sp, Tp), d(Sx, Tp), d(Sp, Tx)\} \\
 &= \delta d(Tx, Sp) + \varphi\{0, 0, d(Sx, Tp), d(Sp, Tx)\} \\
 &\Rightarrow d(Tx, Tp) \leq \delta d(Tx, Sp) + 0 = \delta d(Tx, Tp) \\
 &\Rightarrow d(Tx, Tp) = 0 \\
 &\Rightarrow Tx = Tp \\
 &\Rightarrow x^* = y^*.
 \end{aligned}$$

Thus  $x^*$  is the unique point of coincidence of  $T$  and  $S$ .

Now suppose  $T$  and  $S$  are weakly compatible.

Then, by Proposition 1.7,  $x^*$  is the unique point of coincidence of  $T$  and  $S$ .

The following example supports Theorem 2.7

**Example 2.8:** Let  $(X, d)$  be a complete cone metric space and  $x_0 \in X$  be fixed. Let  $T, S: X \rightarrow X$  be defined by  $Tx = x_0$  for every  $x$  in  $X$ , and  $Sx = x$  for every  $x$  in  $X$ . Then  $T$  and  $S$  satisfy condition (2.7.1) and also  $x_0$  is the unique common fixed point of  $T$  and  $S$ .

### Particular case

Theorem 1.13, the main result of Berinde [4] is a particular case of our main result. It follows as a corollary to our main result (Theorem 2.7) by taking the  $S$ -type control function  $\varphi: P^4 \rightarrow P$  defined by  $\varphi(t_1, t_2, t_3, t_4) = \min \{t_1, t_2, t_3, t_4\}$  assuming that the minimum is meaningful.

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